# On The Use of Loop Subdivision Surfaces for Surrogate Geometry

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# Background

- Desire to reconstruct a smooth surface from a general triangulation
  - Analytic geometry lost (no CAD connection) STLs, CT scans, etc
  - Light-weight substitute for CAD, simple and uniform view (vs. BRep)
- Applications
  - Surface remeshing Need parametrization and evaluation capabilities
  - Inverse evaluations (find closest surface point, "snaps") Need second-derivatives for Newton iterations
  - Direct integration between geometry and solvers (Cut-cell methods, immersed boundary methods, etc)
  - Higher-order element construction
- Challenge: Define the smooth surface, provide required operations

# **Subdivision Surfaces**

- Catmull and Clark (1978), Loop (1987)
- Widely used in the Computer Graphics community
- Generalization of splines to general meshes
- Represent smooth surface by a surface triangulation ("control-mesh")
- $C^2$  almost everywhere, can specify creases and corners
- Fast operations:
  - Subdivision (creating a finer control mesh)
  - Computing normal directions (for lighting)
- Has been implemented in hardware (GPU)

## **Subdivision of Spline Curves**

• Refinement of control polygon:

Current nodes:  $\boldsymbol{x}_{2i}^{j+1} = (\boldsymbol{x}_{i-1}^j + 6\boldsymbol{x}_i^j + \boldsymbol{x}_{i+1}^j)/8$ New midpoints:  $\boldsymbol{x}_{2i+1}^{j+1} = (\boldsymbol{x}_i^j + \boldsymbol{x}_{i+1}^j)/2.$ 

• Limiting node positions:

Current nodes: 
$$x_i^{j,\infty} = (x_{i-1}^j + 4x_i^j + x_{i+1}^j)/6.$$



# **The Loop Subdivision Scheme**

- Compute locations of new vertices as weighted average of original vertices
- Local neighborhood gives compact support
- Limiting node positions computed by similar scheme



# **The Loop Subdivision Scheme**

- In Computer Graphics, refine until sufficiently fine for visualization and normal directions (parametrization not required)
- Non-interpolating: Some shrinkage depending on smoothness
- Surface  $C^2$  continuous everywhere except at irregular nodes



One Refinement

**Two Refinements** 





# Hard Edges and Vertices

- Can specify triangle edge as "hard" (creases) reduces to a spline curve
- For general input triangulations: Automatically detect hard edges/vertices based on angle criteria



## **Evaluation and Parametrization**

- Subdivision scheme can generate arbitrarily fine approximations of surface
- Our applications need general parametrization and evaluation capabilities
- Well-known expressions for spline curves, with four consecutive nodes

 $\boldsymbol{x}_{i-1},\ldots,\boldsymbol{x}_{i+2}$ , parameter value  $t\in[0,1]$  between node i and i+1:

$$\boldsymbol{x}(t) = \begin{bmatrix} t^3 & t^2 & t & 1 \end{bmatrix} \frac{1}{6} \begin{bmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 3 & 0 \\ -3 & 0 & 3 & 0 \\ 1 & 4 & 1 & 0 \end{bmatrix} \begin{bmatrix} \boldsymbol{x}_{i-1} \\ \boldsymbol{x}_i \\ \boldsymbol{x}_i \\ \boldsymbol{x}_{i+1} \\ \boldsymbol{x}_{i+2} \end{bmatrix}$$

• Differentiate analytically for normals and curvatures

## **Parametrization – Regular Triangles**

- In a regular triangle, the Loop scheme reduces to the common box splines
- Evaluate for arbitrary v, w by linear operation  $\boldsymbol{x}(v, w) = \boldsymbol{x} \boldsymbol{\phi} \boldsymbol{c}(v, w)$ , with local node locations  $\boldsymbol{x}$  and monomial coefficients  $\boldsymbol{c}(v, w)$
- Precomputed constant matrix  $\phi$  (see paper for details)

Local Node Numbering



**Local Coordinates** 



# **Parametrization – Irregular Triangles**

- Main idea [Stam 1998]: Subdivision introduces new triangles with regular neighborhoods, which can be evaluated as box splines
- Close to irregular nodes, large number of refinement might be required
  - Stam solved this using the eigen-decomposition of refinement matrix
  - Simpler hack: Nudge requested position to center after 25 subdivisions
- Implementation: Local representation of triangle neighborhood
  - Too expensive to refine entire mesh



# **The Evaluation Algorithm**

function [x, dx, ddx] = loopeval(t, v, w, depth)

 $\quad \text{if }t \text{ regular} \\$ 

Evaluate surface location and derivatives using box-spline expressions

#### else

Subdivide t and all triangles sharing its nodes

if  $depth \leq 25$  t' = new triangle covering v, w v', w' = new local coordinates in t'else t' = center subtriangle v', w' = new local coordinates (on edge of subtriangle)end if [x', dx', ddx'] = loopeval(t', v', w', depth + 1)Inverse mapping:  $x = x', dx = \pm dx'/2, ddx = ddx'/4$ end if

# **Creating an Interpolating Scheme**

- The interpolating subdivision schemes produce less smooth surfaces
- Alternative: Solve for new control-mesh mesh nodes in  $S^{\infty}(\boldsymbol{x}_{\mathrm{interp}}) = \boldsymbol{x}$ 
  - Well-conditioned, solve using a few Krylov iterations
  - Good for uniform smooth control-meshes, but might produce cusps



# **Example: Flap**

- Simple mesh refinement for real-world geometries provided in STL format
- Demonstration of arbitrary parameter evaluation, not high-quality meshing



# **Example: Viking Spacecraft Aeroshell**



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## **Example: Scanned Foam Piece**



# **Example: Pig**



## Conclusions

- Use subdivision surfaces as surrogate for real CAD geometry
- Simple implementation, uniform view
- Remeshing, adaptation, inverse evaluations, etc
- TURIN the Tetrahedral Unstructured Remeshing INterface
  - Contact Bob Haimes (haimes@mit.edu) for more information



